



ASHOK LEYLAND

Koi Manzil Door Nahin

Virtual Validation of Warning-Based ADAS Features



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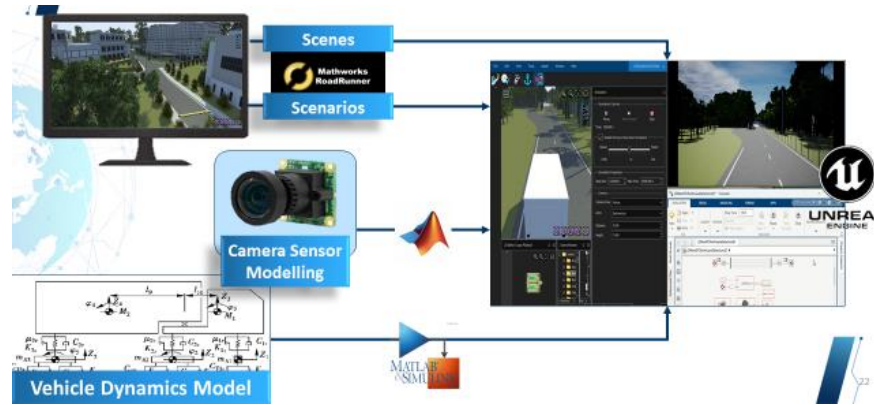
Divya T
Software Developer
Ashok Leyland



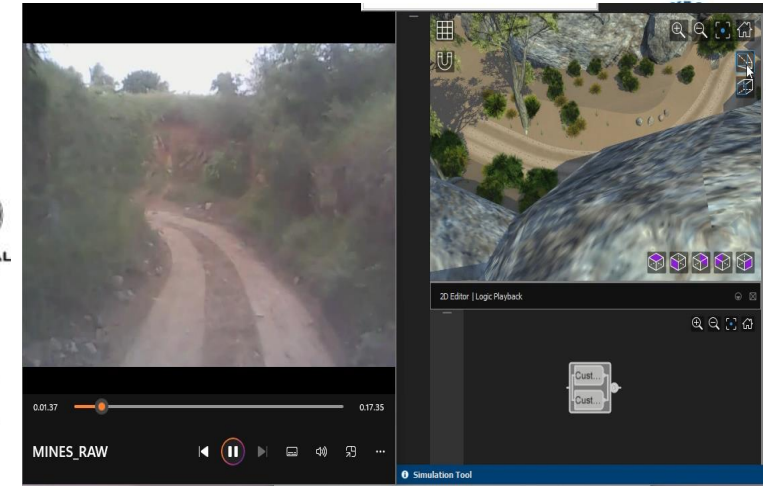
HINDUJA GROUP

Agenda

- Software-Defined-Vehicle
- Levels of ADAS features
- Software development process
- ADAS Simulation & Validation
- Software in loop testing
- Co-simulation platforms



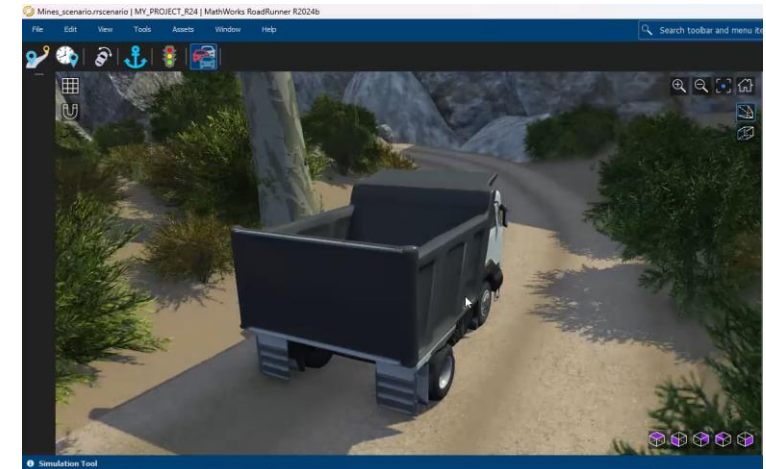
Co-Simulation



Real World Comparison



Realistic 3D Assets for Perception Validation



Custom 3D Scenes

Software-Defined-vehicle



DATA Integration



Optimization



Safety



Enhanced Connectivity



Continuous Improvement

Key Benefits:

1. Enhanced Safety by react faster in critical situations
2. Enhanced performance and efficiency of optimized vehicle dynamics
3. Personalized driving experience and Predictive maintenance.

ADAS

Advanced Driver Assistance System

**Regulations by
2028**

**Indian Environment
Adaptation**

Critical Scenarios

Safety Features

ADAS Levels



Full Automation

Driverless



Level 5

Conditional Automation

Vehicle can operate under limited conditions



Level 4

Partial Automation

Driver does not need to observe but must be ready to resume



Level 3

Driver Assistance

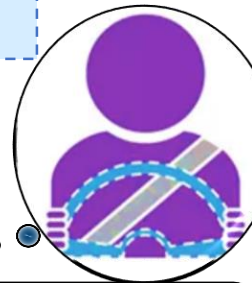
Driver must observe the drive and be ready to take control



Level 2

No Automation

The driver always controls all driving functions



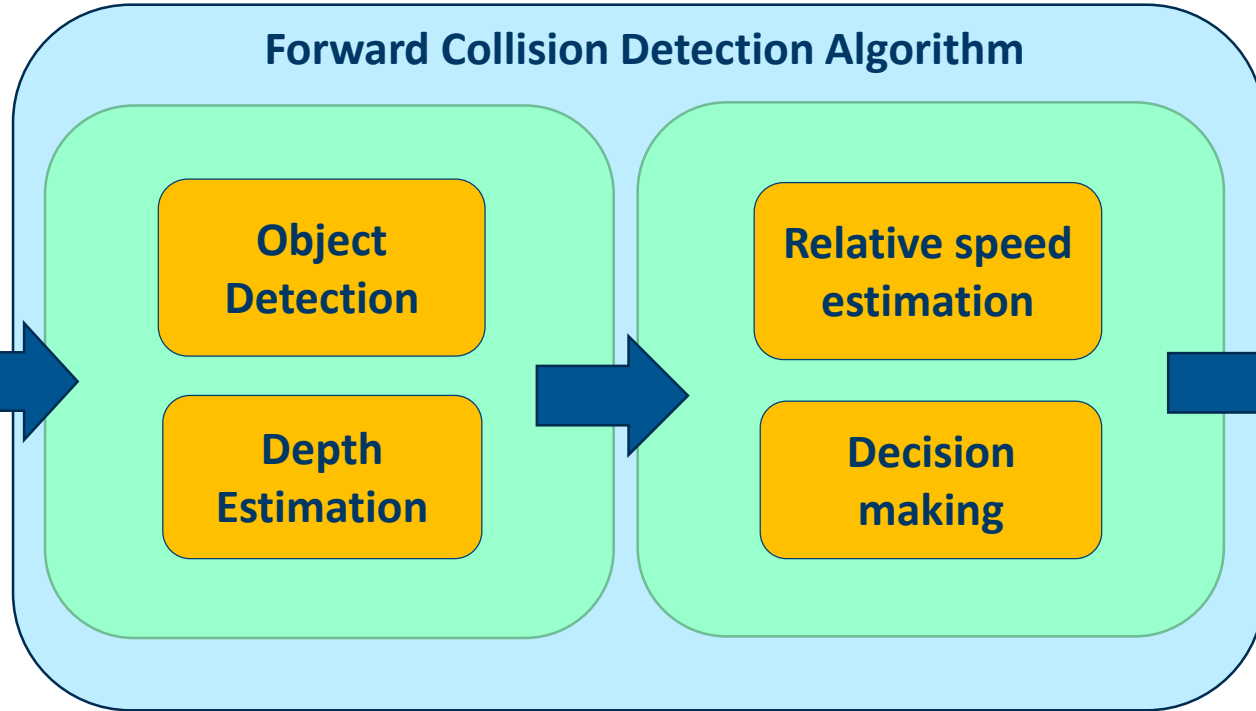
Level 1

Level 0

Forward collision warning system



Input image from camera

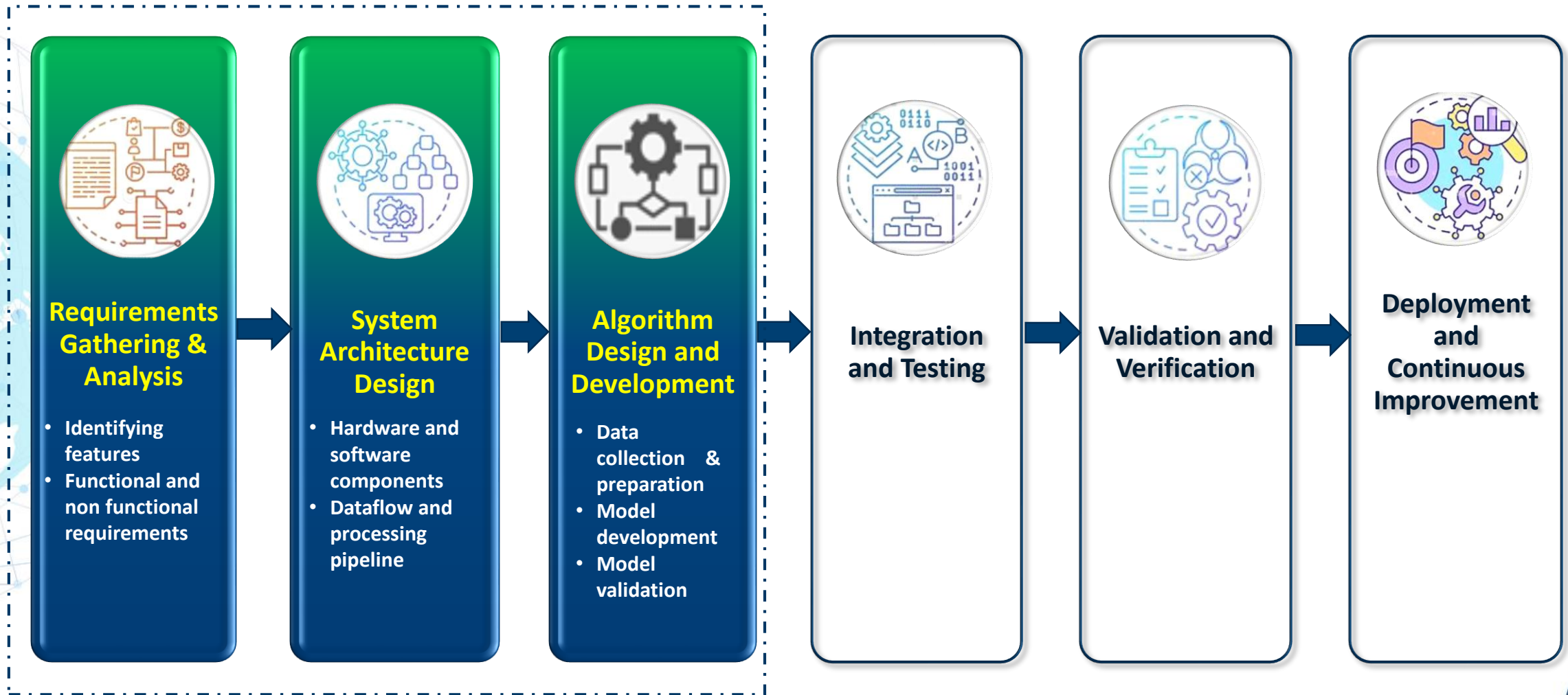


Vehicle speed

Collision Warning



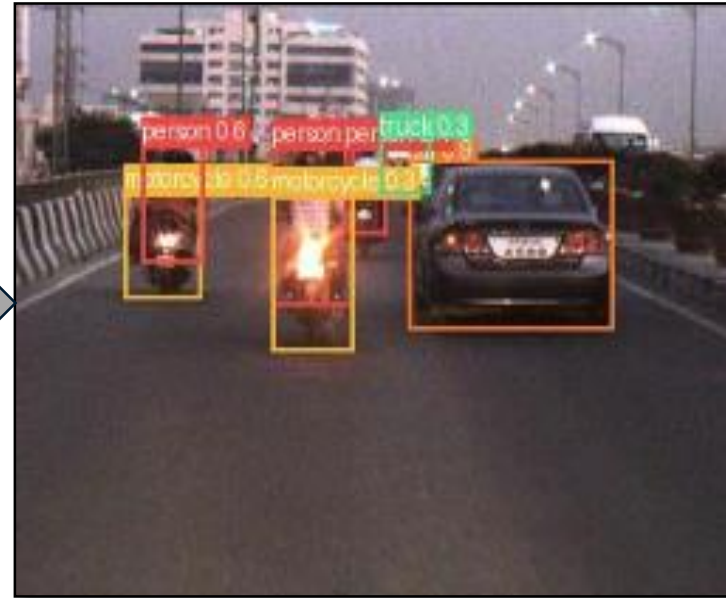
Software Development Process



Data collection and Preparation



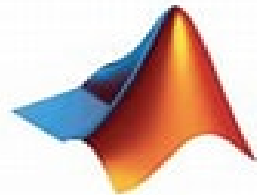
Data collection



Data annotation

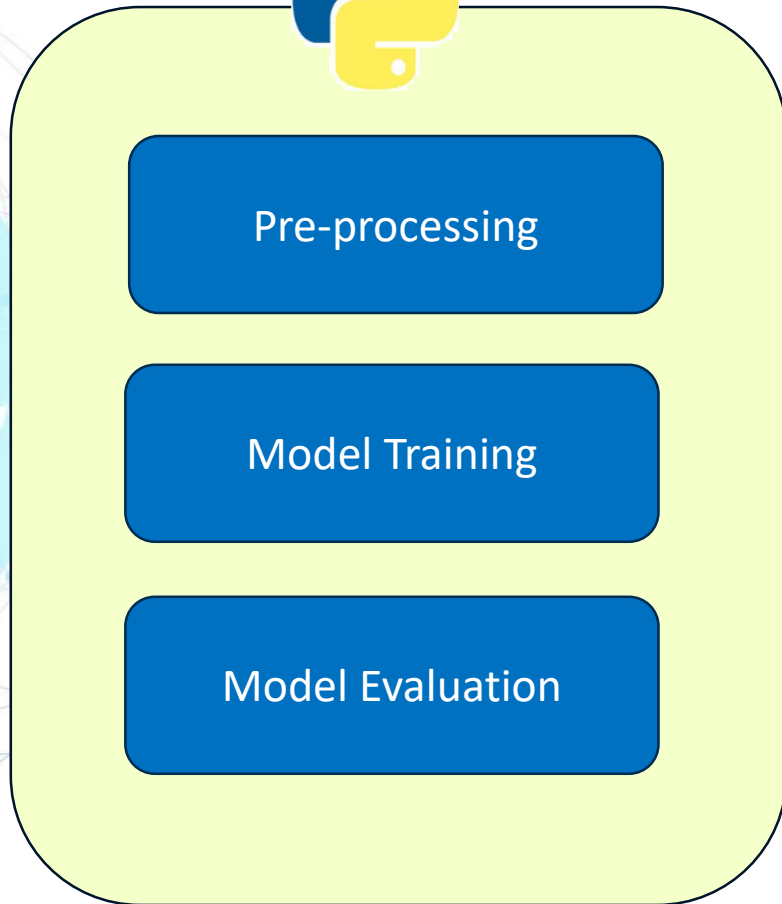
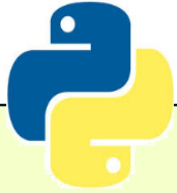
Challenges in Real time data collection:

- High data volume
- Hardware limitations
- Scenario limitations
- Changing Environments

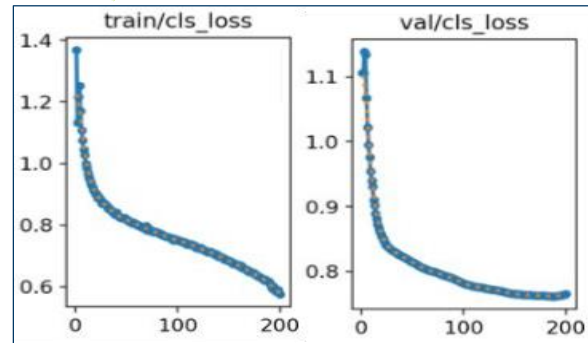
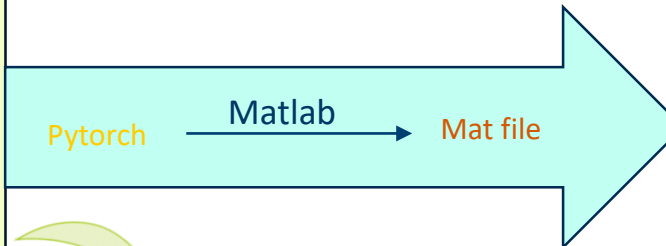


- Synthetic data generation
- Automatic annotation

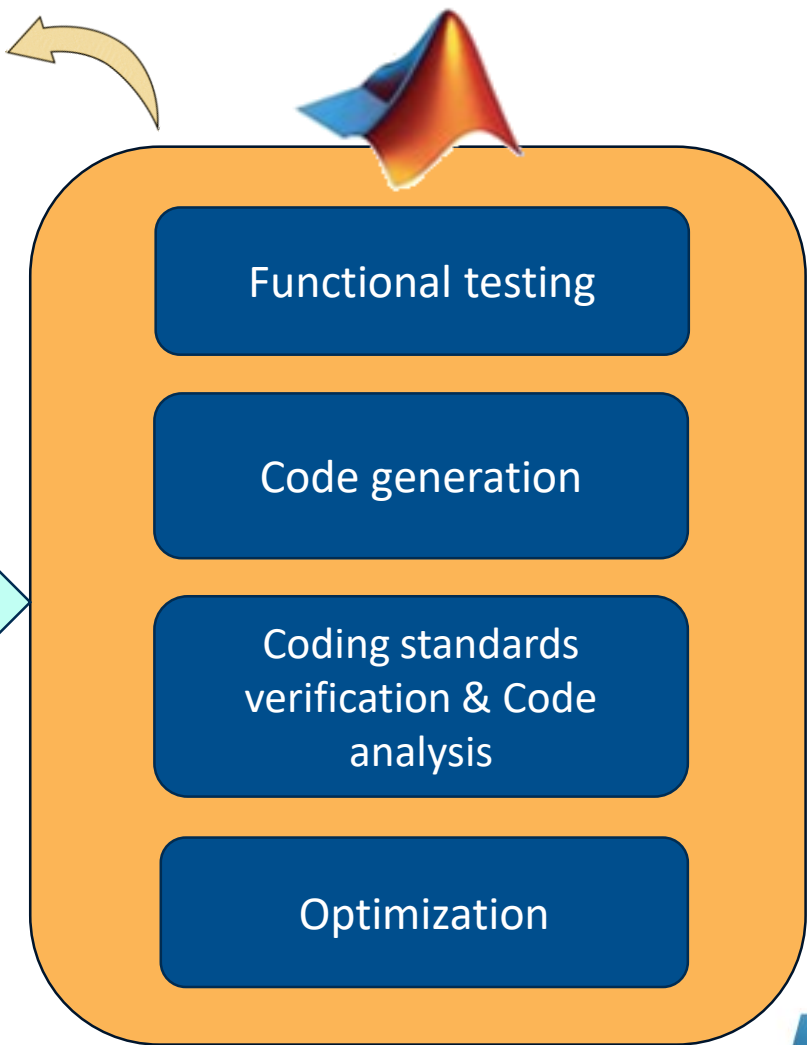
Model Development and Validation



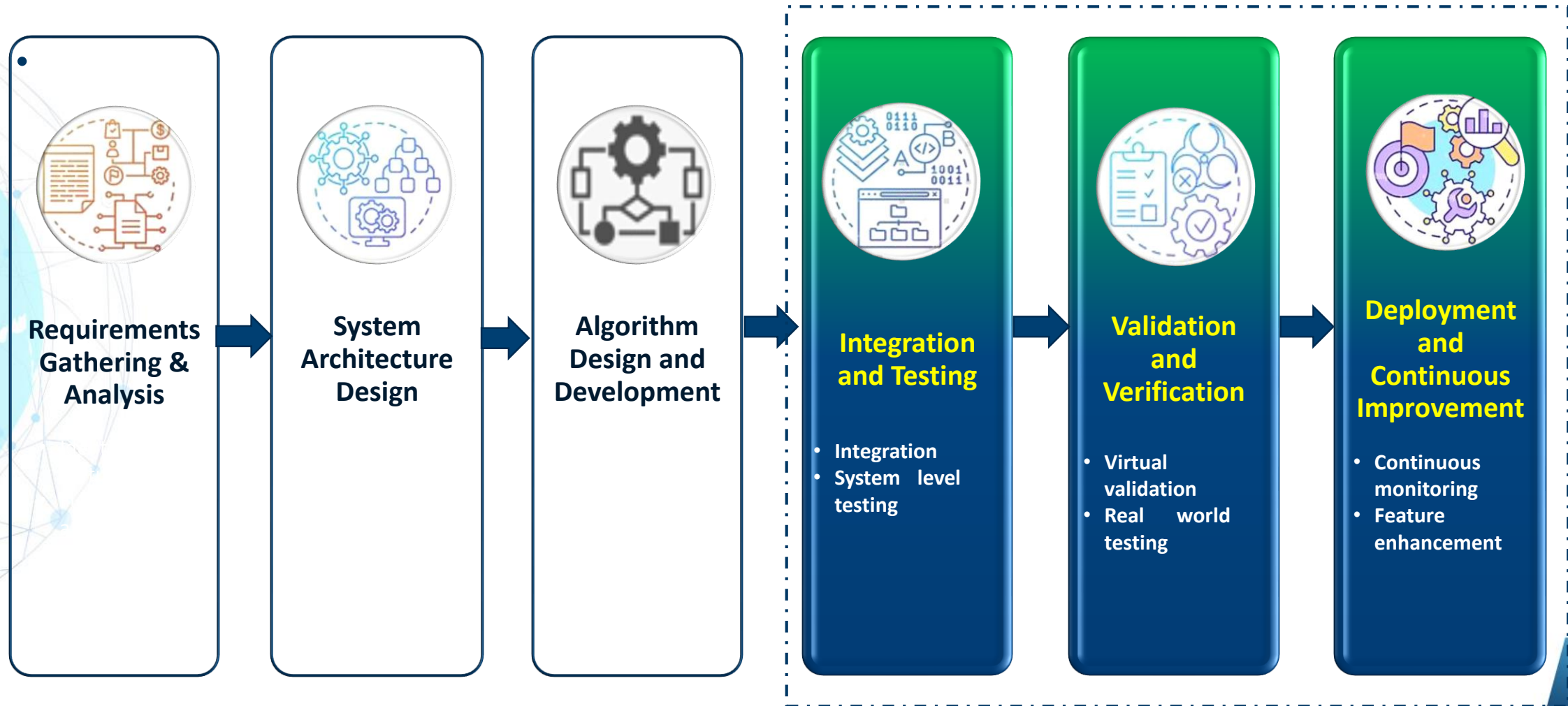
Validation result of object detection and depth estimation models



Training process of deep learning model



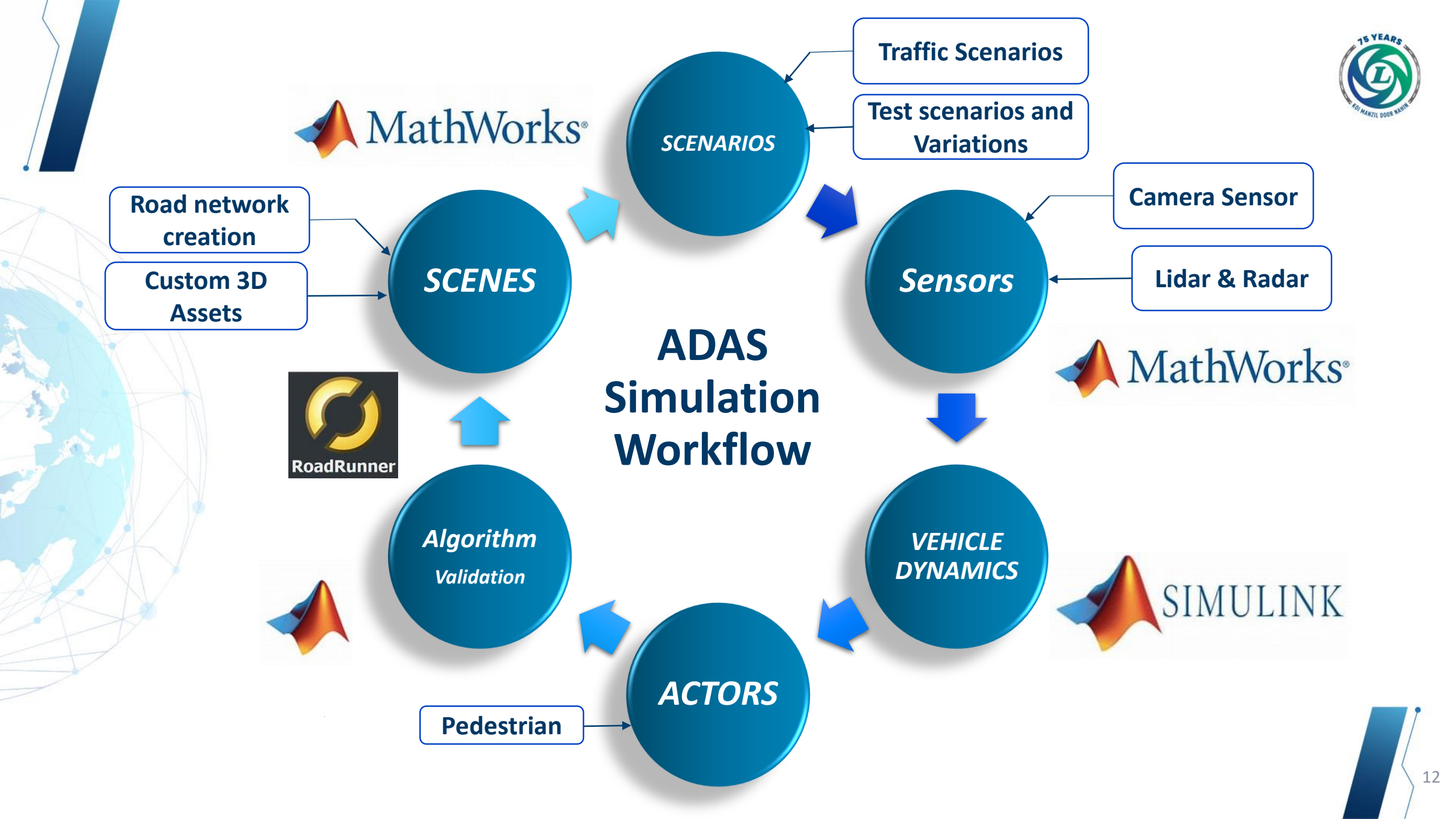
Software Development Process



Challenges in Indian Scenarios

- Unpredictable road conditions
- Variable lane widths
- Poor road markings
- Pedestrian
- Non- motorized vehicles
- Erratic Driving behavior
- Chaotic traffic conditions





Scene creation

Customized Environment creation for Indian roads



Ease to create complicated road networks

Traffic sign boards



Climatic Conditions

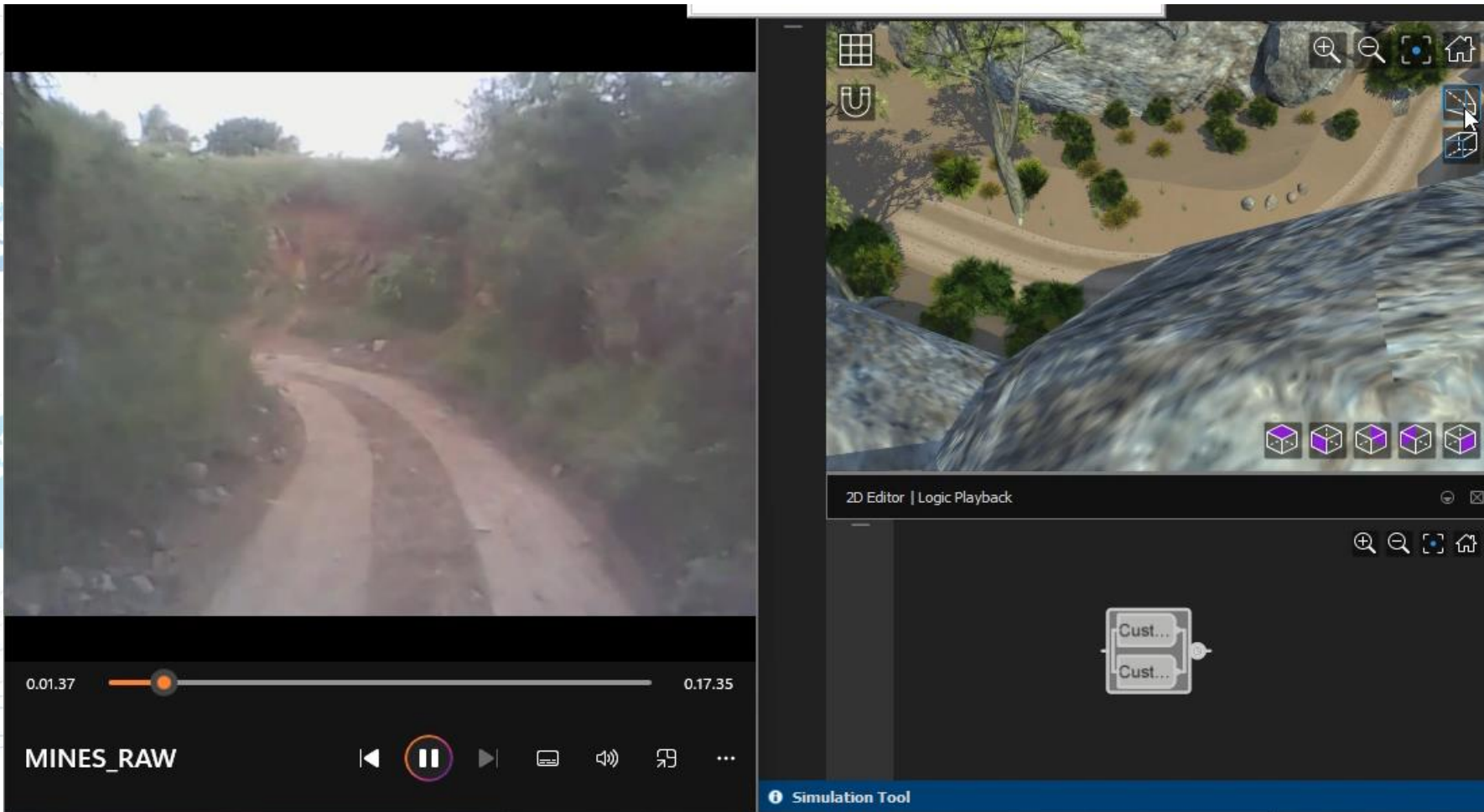


Ashok Leyland Technical Centre Infrastructure

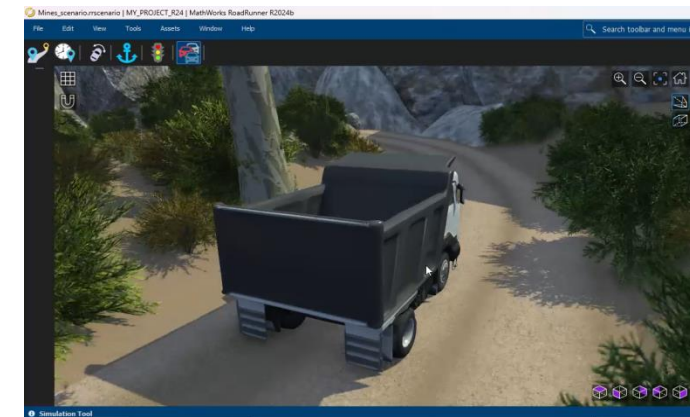


Environment creation

Scene creation using Roadrunner



Highway Environment



Mines muddy Road

Gen-AI 3D Assets

Image to 3d Asset Generation

Image Input



*Processed using
Matlab and
python*



Output as Obj



CHALLENGES:

- Lack of Indian Assets to train the perception models.
- Cost of collecting real World Data



Exported .Fbx file can be used in Roadrunner for customized Assets and scenarios.

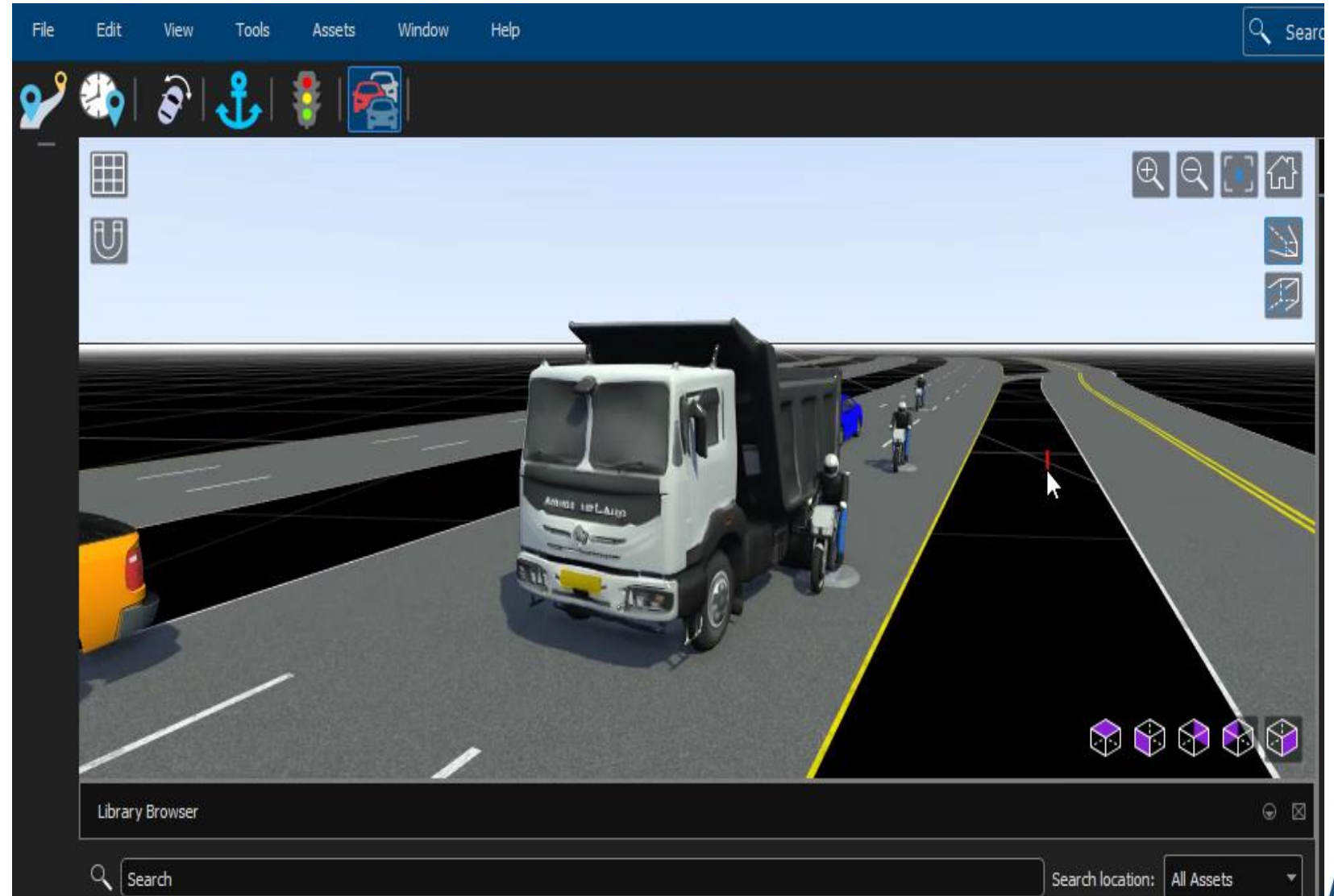
Scenario creation

Scenarios with Custom Assets

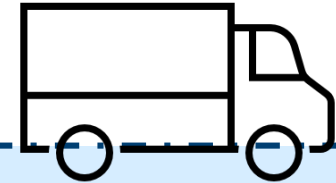
Indian Scenarios

Euro NCAP Test Scenarios

Test Automation



Vehicle Dynamics Modelling



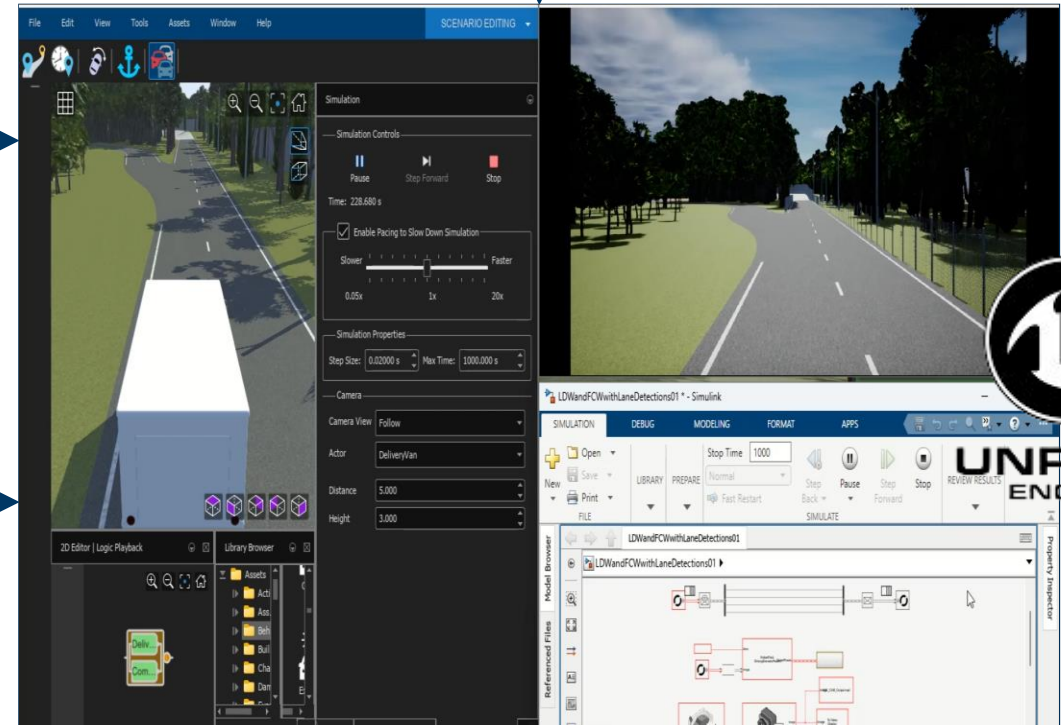
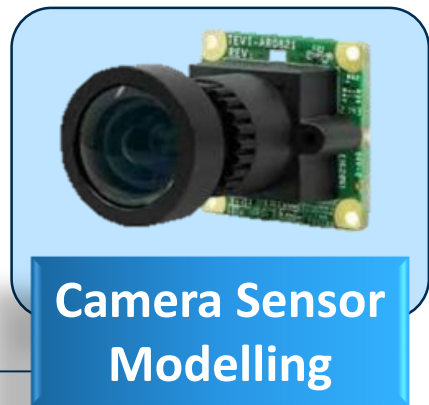
- ✓ High Fidelity dynamics
- ✓ Customized vehicle
- ✓ Test Various Models
- ✓ Data Retrieving

Software in the Loop Testing

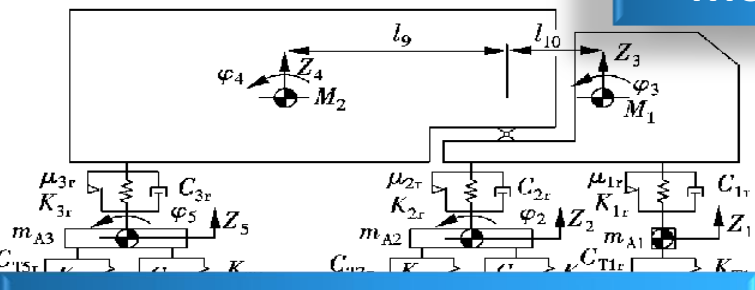
ADAS Simulation



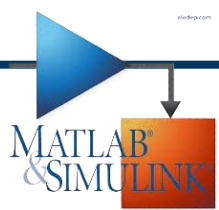
Co-simulation Workflow



UNREAL ENGINE



Vehicle Dynamics Model



Co-simulation with Unreal Engine

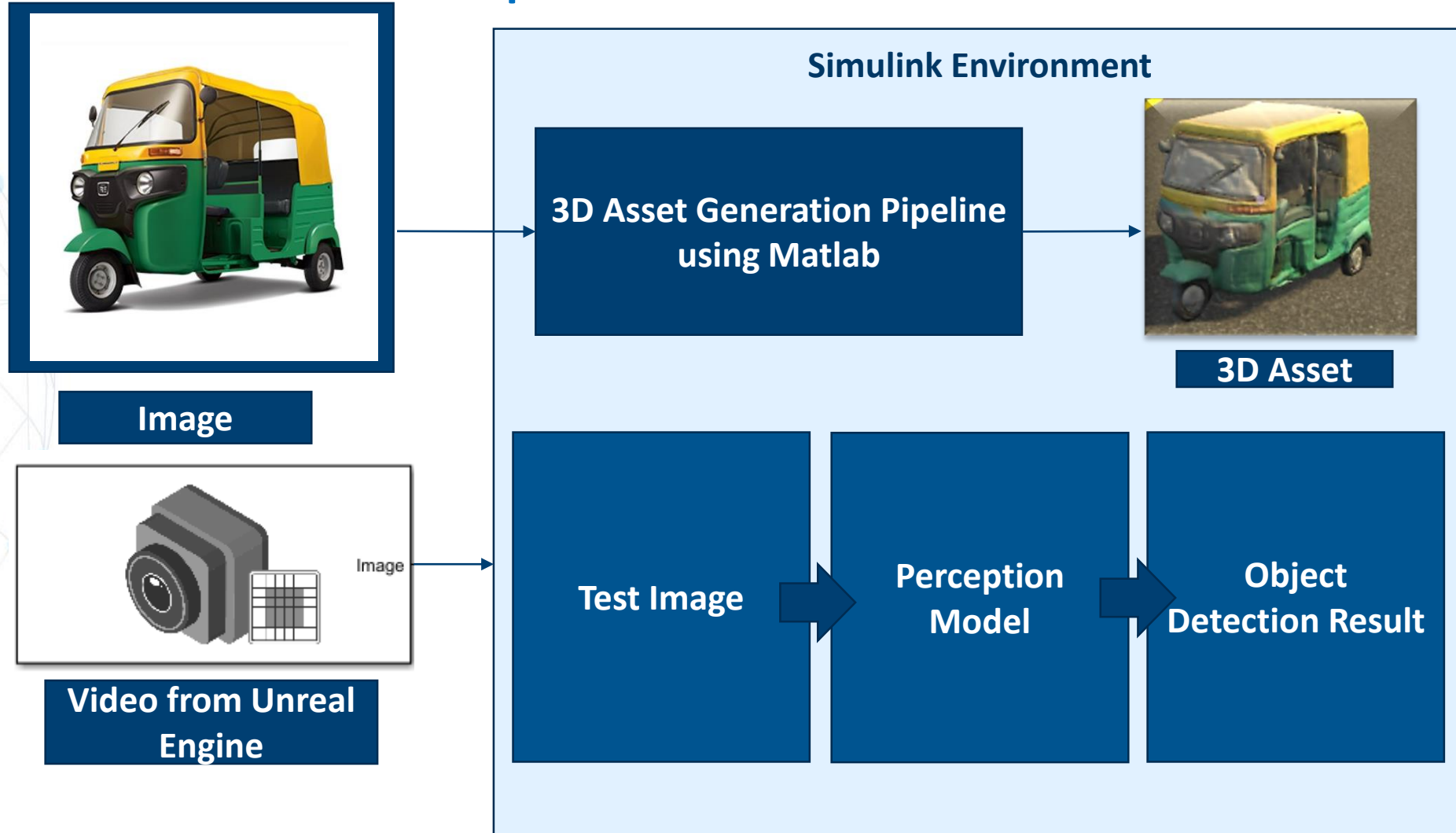
The screenshot displays the MathWorks RoadRunner R2023b interface. The top window shows a 3D simulation of a road scene with a white van. The middle window shows simulation controls, including a play button, a speed slider (0.05x to 20x), and simulation properties (Step Size: 0.02000 s, Max Time: 1000.000 s). The bottom window shows a Simulink model diagram with a yellow warning message: "To create a connection, click a port, terminator, or line segment, and then click a compatible, highlighted model element. More information. Do not show again." The status bar at the bottom indicates "Running" and "View diagnostics 26% [Zoom in for more editing features] T=16.443 1% ode23tb".

Key Simulation Output:

- ✓ Validating ADAS Algorithm with various test cases and scenarios
- ✓ Test Automation of Scenarios
- ✓ To ensure the safety and robust of the ADAS features

FCW Validation Workflow

Realistic 3D Assets for Perception Validation

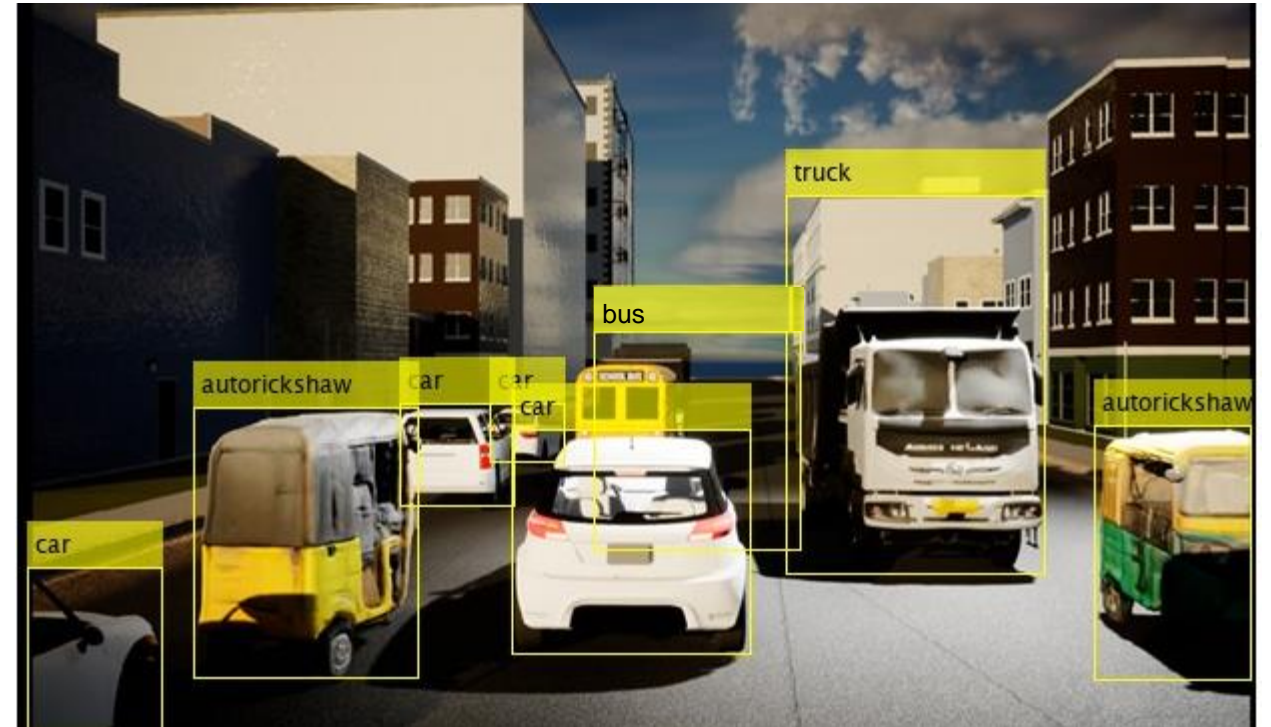


Object Detection

With realistic 3D Assets

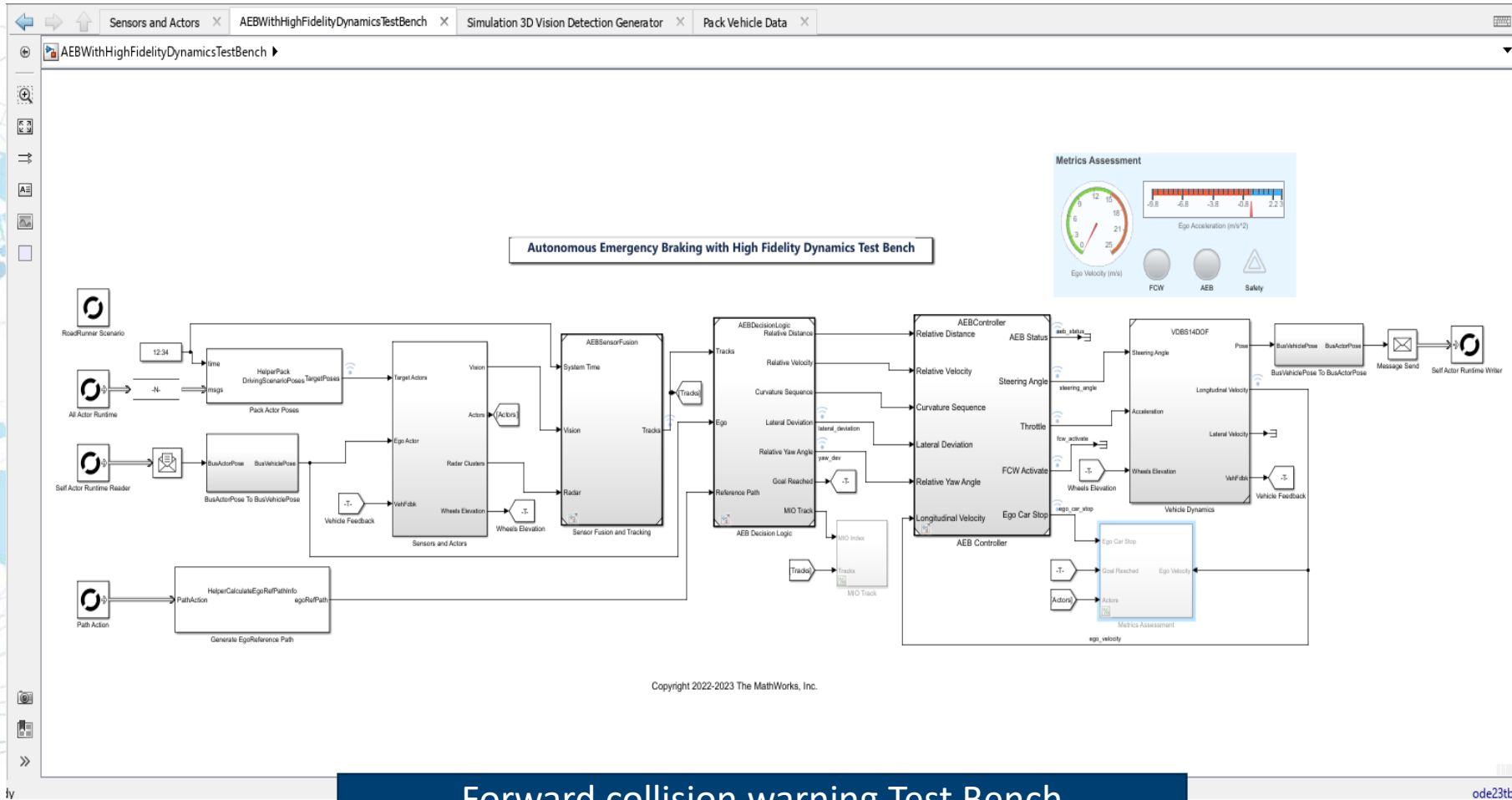


Real World Environment



Virtual Simulation Environment

FCW validation



Validation Result:

- ✓ Depth Estimation
- ✓ FCW warning System

Forward collision warning Test Bench



Benefits



Time Reduction



Train critical scenarios



Cost Reduction

Thank you

Koi Manzil Door Nahin!

