

Simulink Test를 이용한 Powertrain Blockset 기반의 동적 검증

홍 혁 기



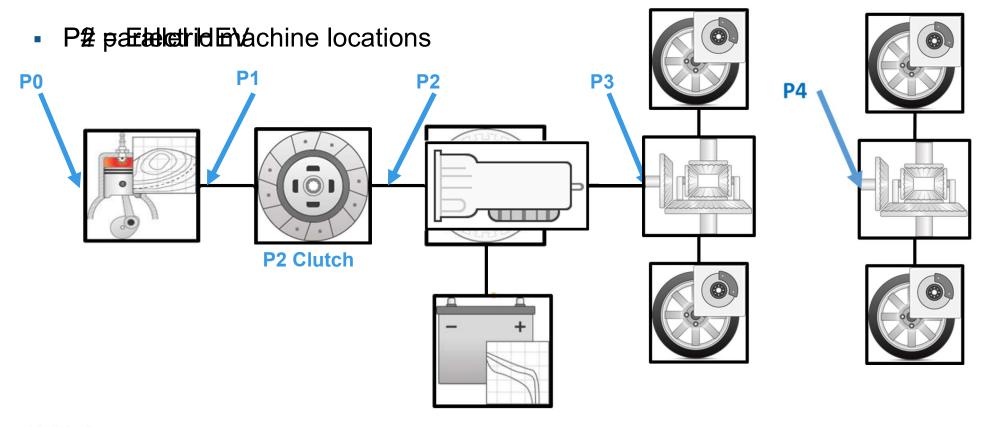


Agenda

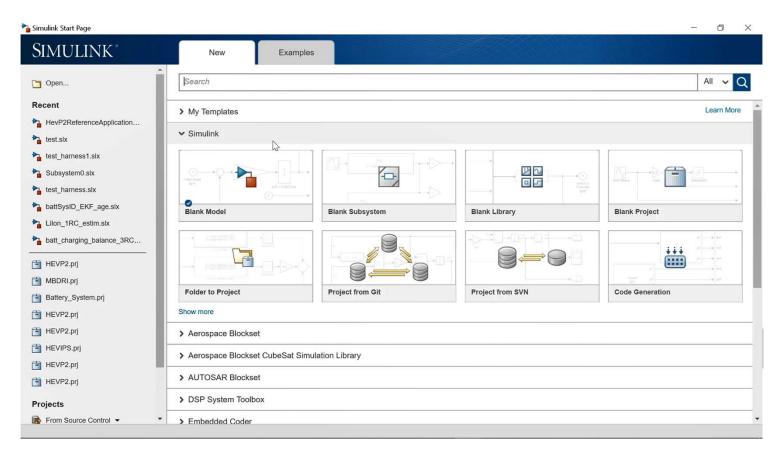
- HEV P2 Model
- Requirement Management in the Simulink Enviornment
- How to implement VnV Activities using Simulink Test with HVE P2 Model
 - Case1: HVE P2 Performance
 - Case2 : HVE P2 Fuel Economy



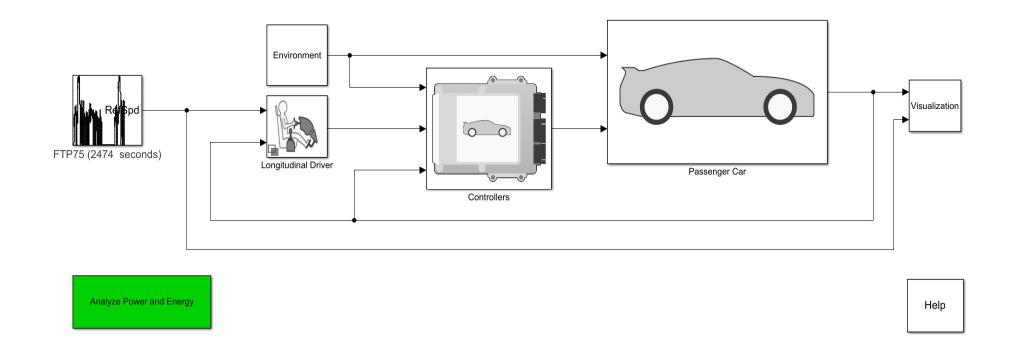
Nomenclature for HEV Topology



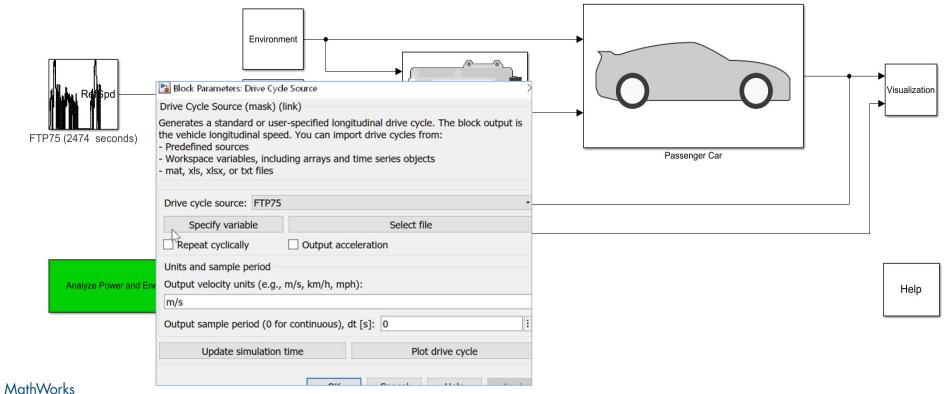




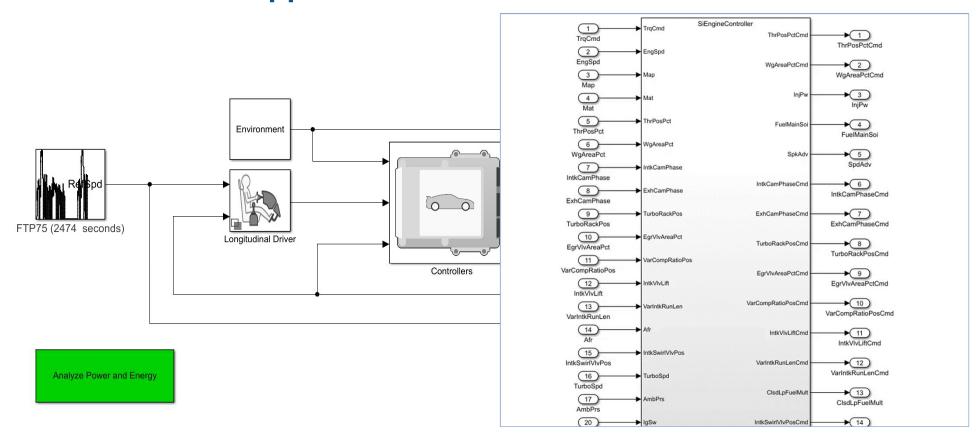




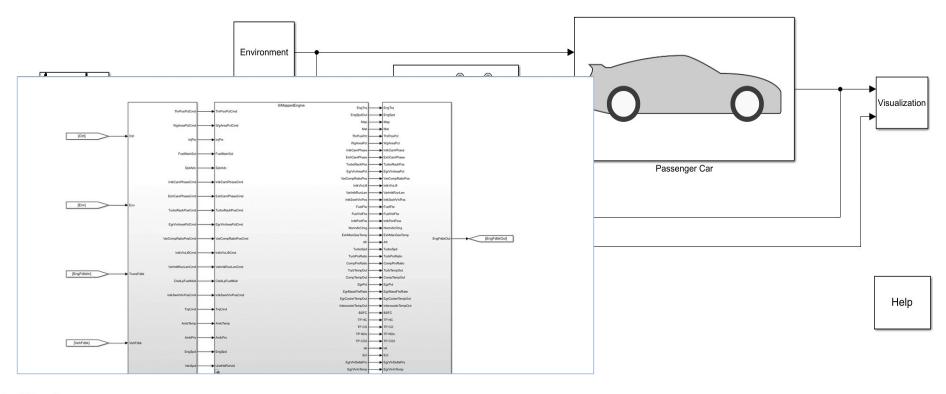




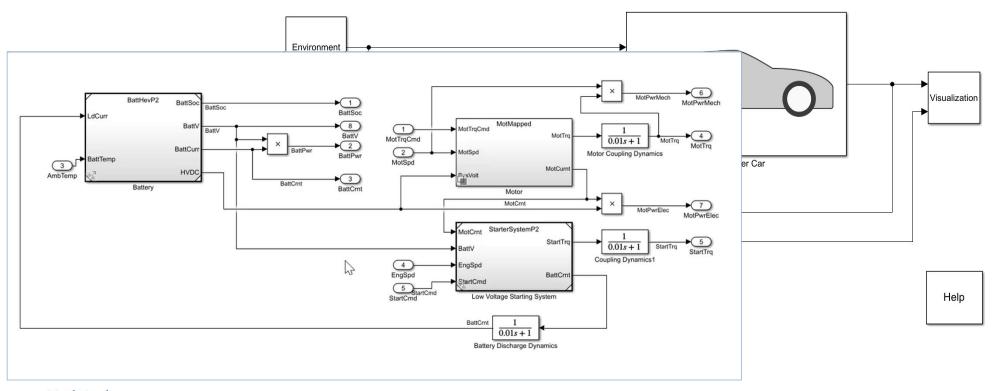












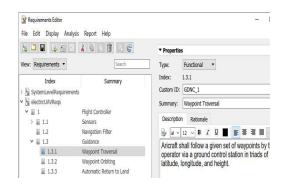


Powertrain Blockset / Simulink Test Collaboration

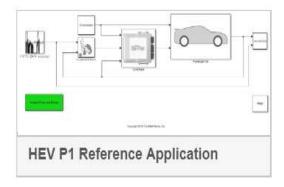
- Plus
 - Provide starting point for engineers to build good plant / controller models
 - Provide <u>open</u> and documented models
 - Provide very <u>fast</u>-running models that work with popular HIL systems
- Needs
 - Systematic V&V workflow using Powertrain Blockset
 - Repeatable and Automatic Process



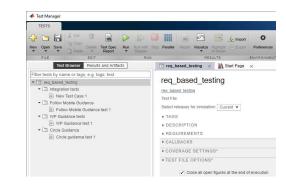
Model Based Design for Powertrain Blockset



- Simulink Requirement
 - Test Requirement Authoring
 - Test and Modeling Status Check



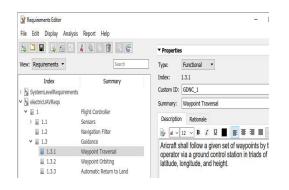
- Powertrain Blockset
 - Vehicle modeling
 - Simulation

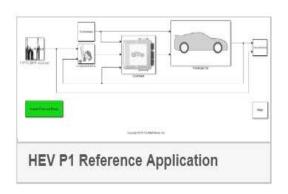


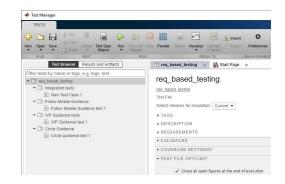
- Simulink Test
 - Test Authoring and Automation
 - Execution and Report Generation



Model Based Design for Powertrain Blockset



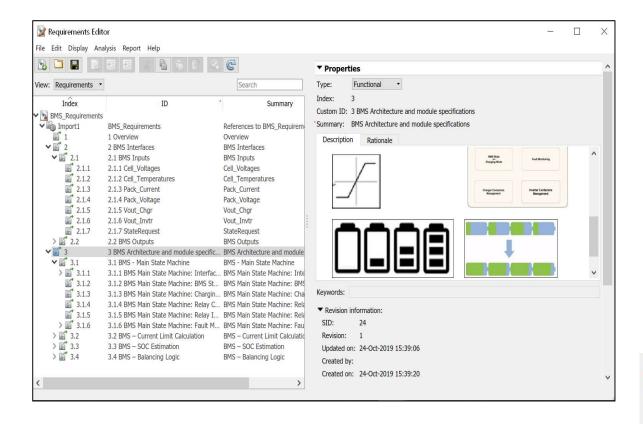


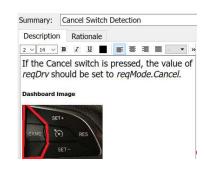




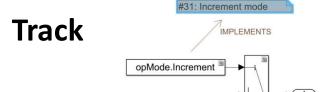


Author Requirements in Simulink





Author

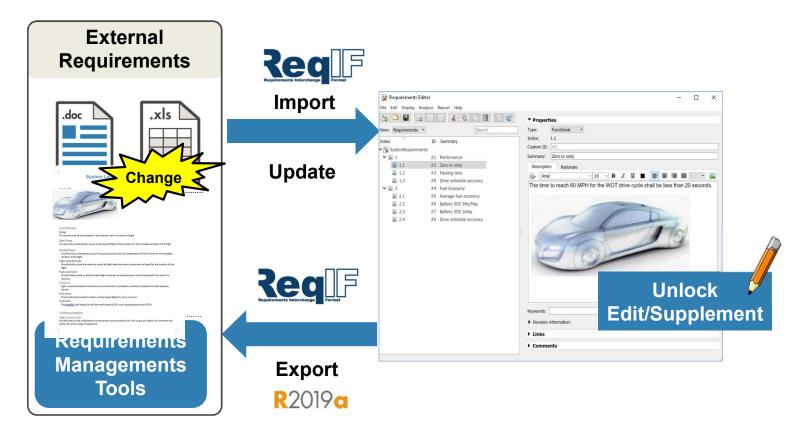




Manage

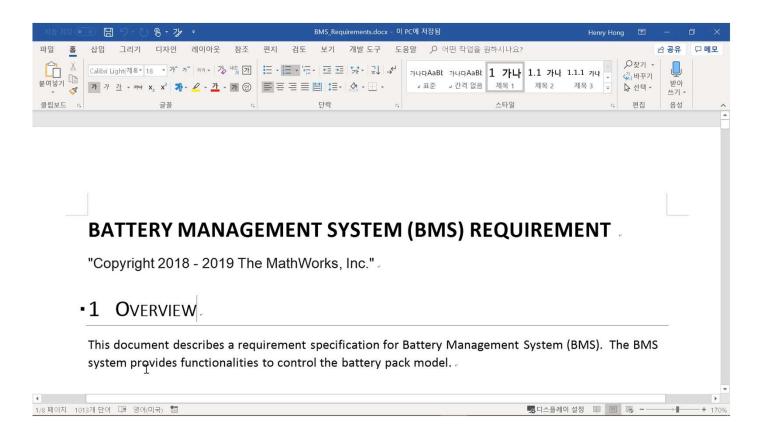


Import and Export with External Tools



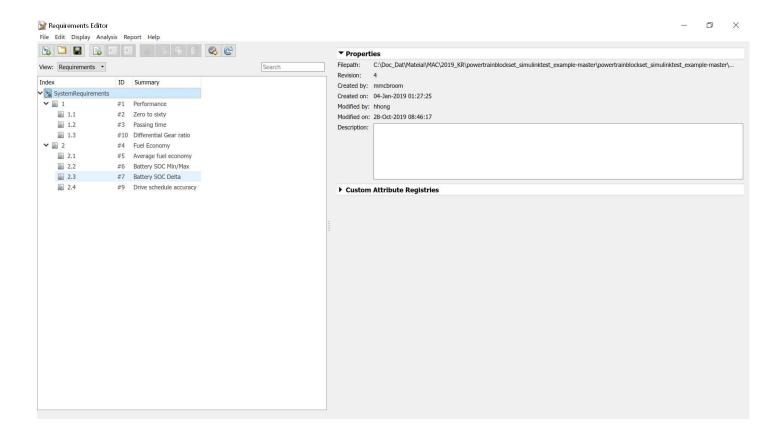


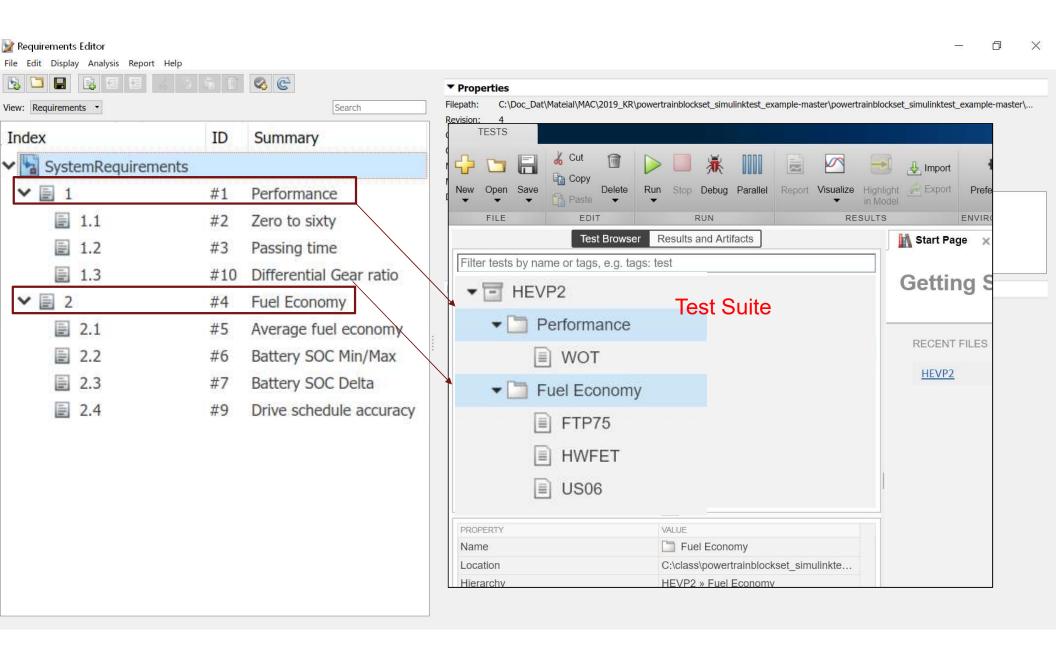
Import External Requirements

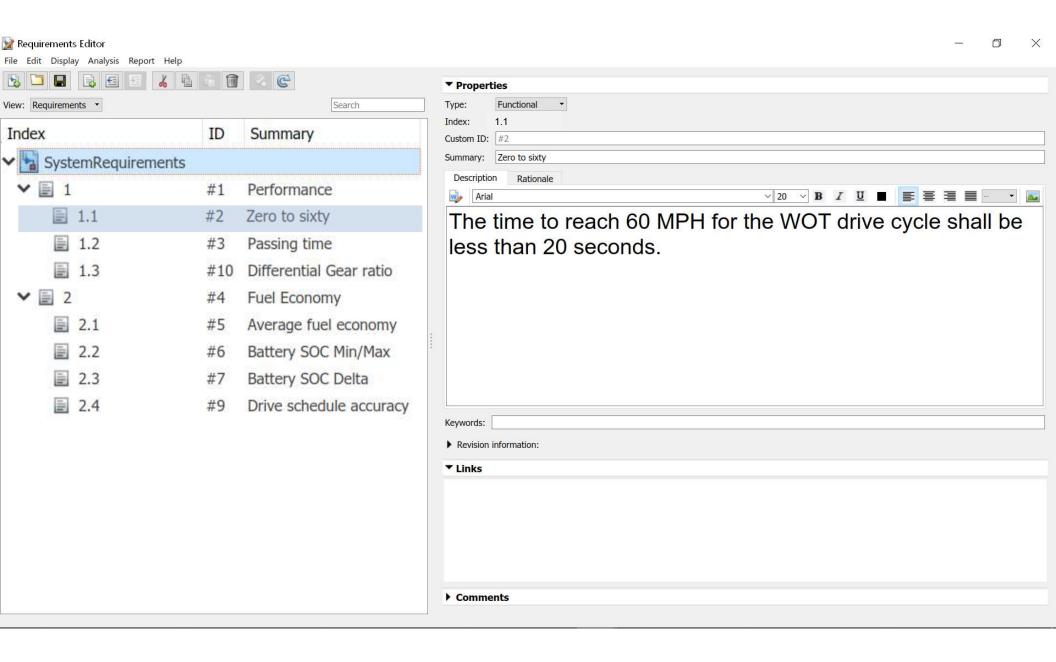


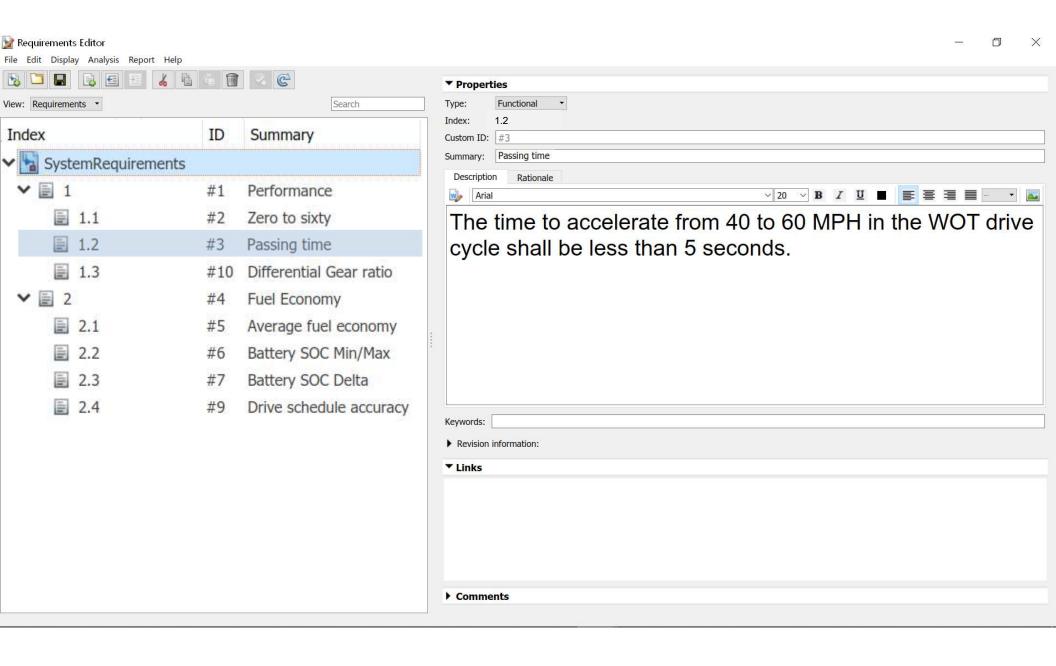


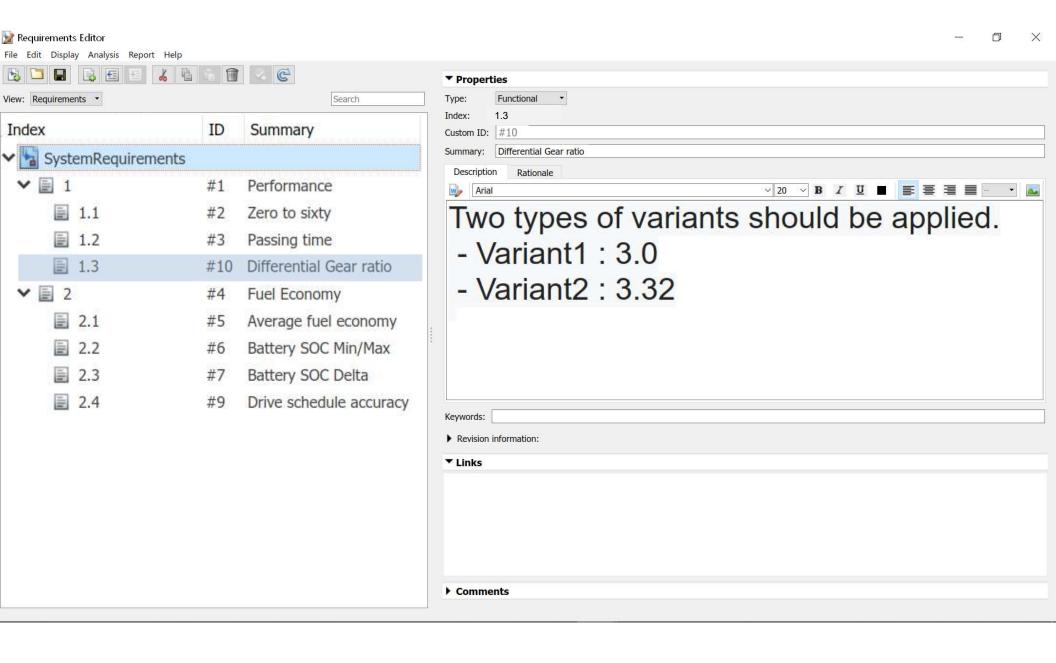
HEV P2 Test Requirement

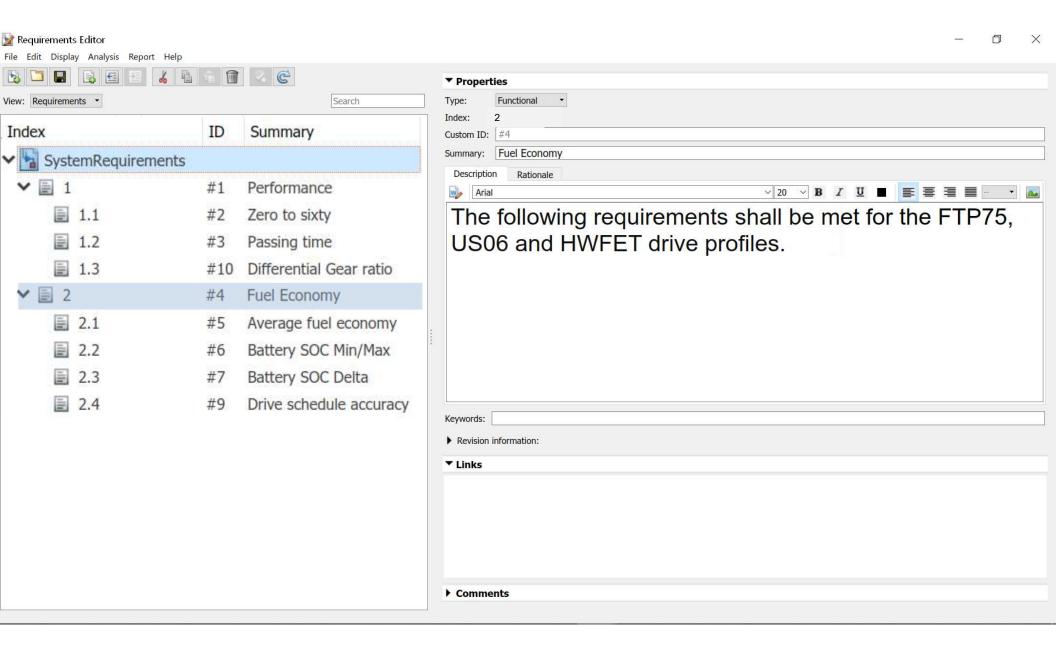


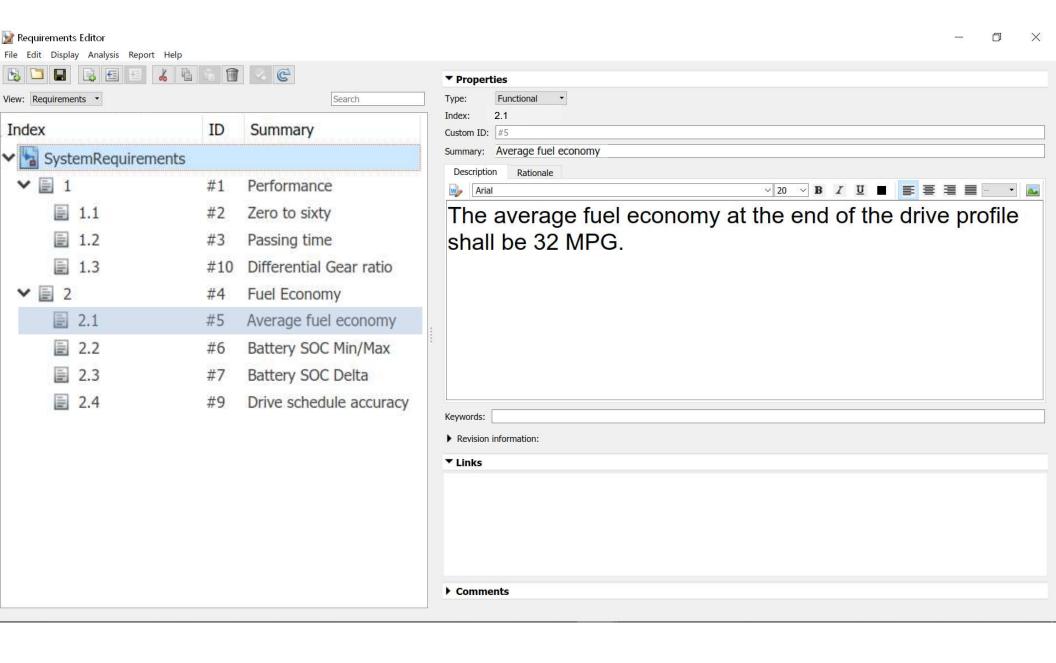


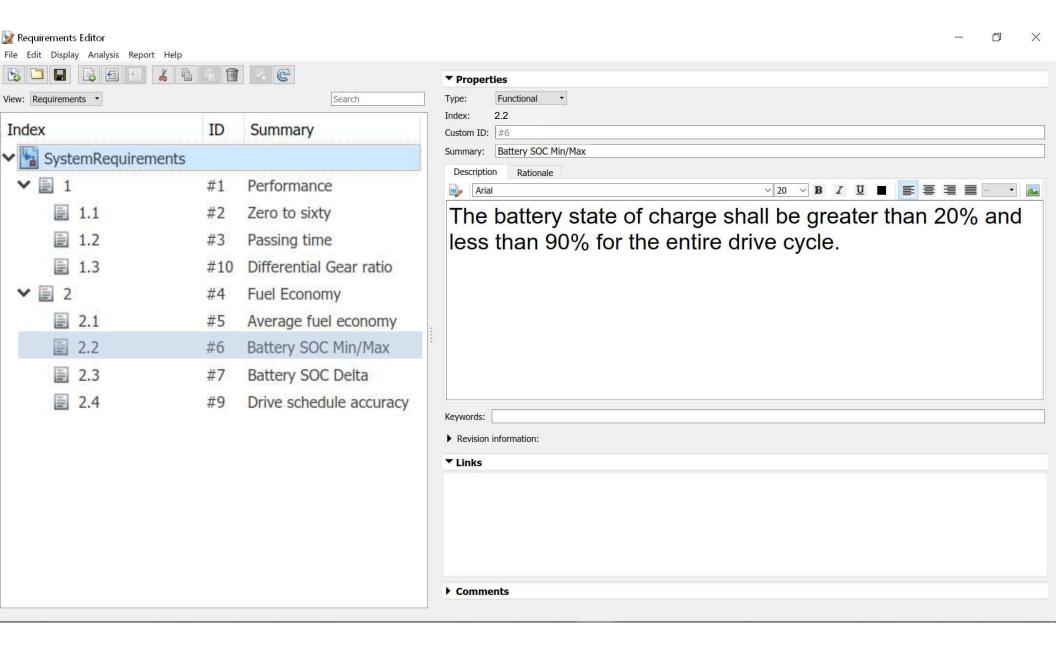


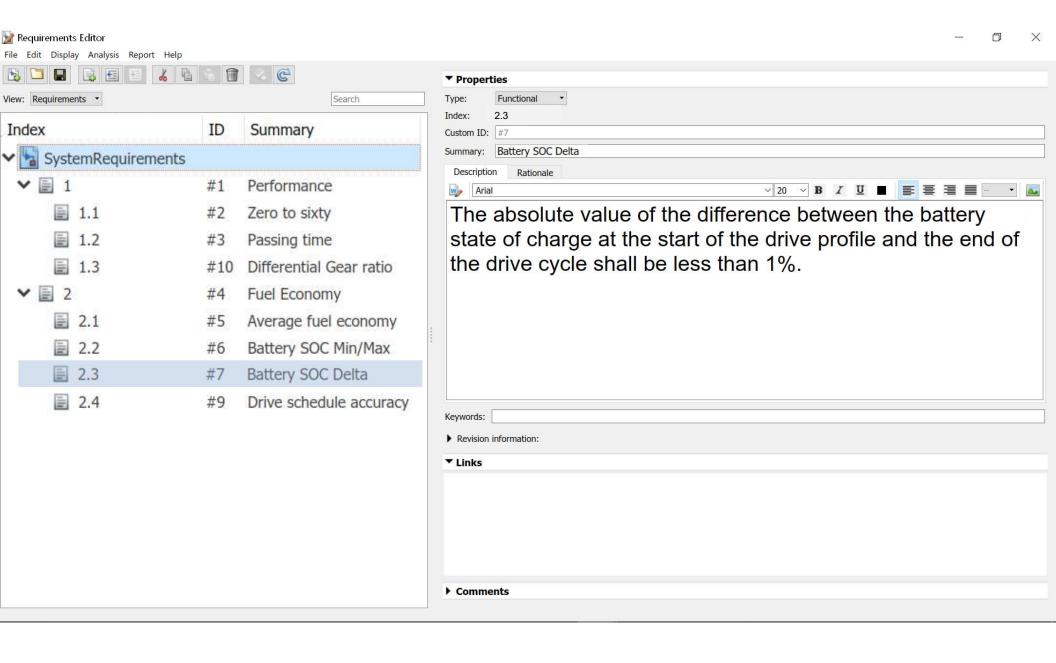


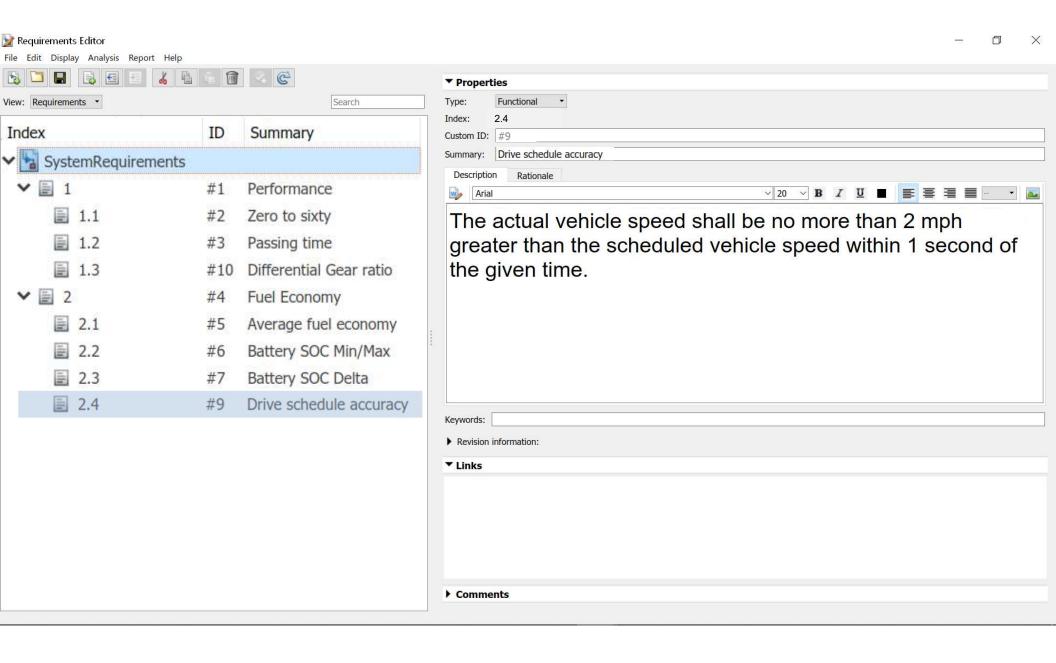






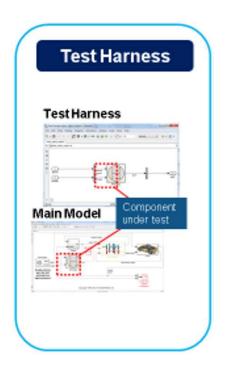




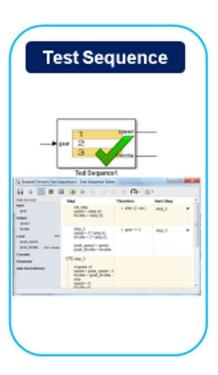




Simulink Test







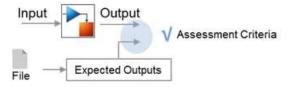


Test Case Templates

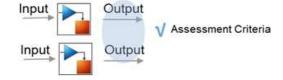
Simulation Testing

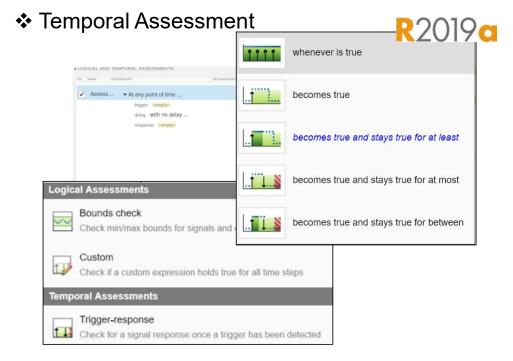


❖ Baseline Testing : Regression Test



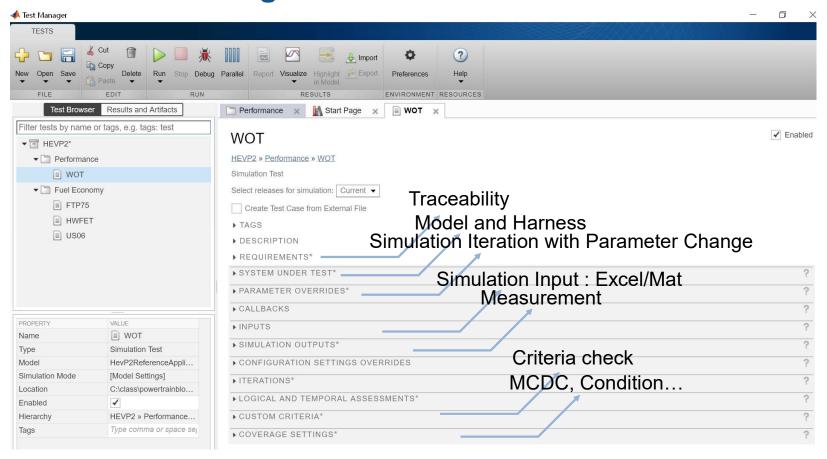
Equivalence Testing





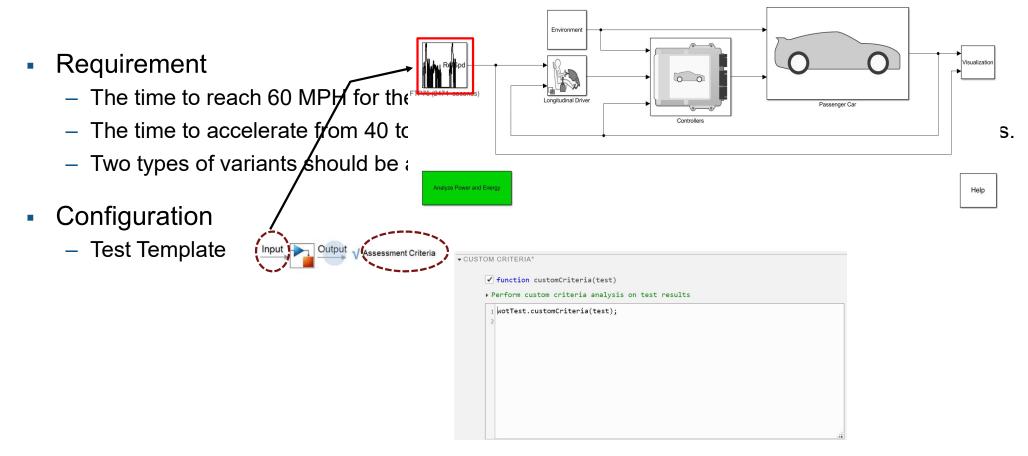


Simulink Test Configuration





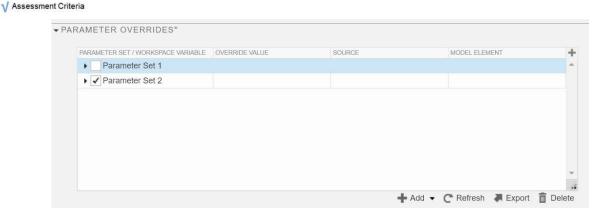
Dynamic Test 1 - Performance





Dynamic Test 1 - Performance

- Requirement
 - The time to reach 60 MPH for the WOT drive cycle shall be less than 20 seconds.
 - The time to accelerate from 40 to 60 MPH in the WOT drive cycle shall be less than 5 seconds.
 - ─ Two types of variants should be applied. (Variant1 : 3.0 / Variant1 : 3.32)
- Configuration
 - Test Template
 - Test Measurement
 - Target Speed
 - Actual Speed
 - Parameter Variant Control
 - Parameter Override





```
function customCriteria(test)
    try
        vs = test.sltest simout.logsout.get(1).Values;
       Output / Assessment Criteria peed till that actual speed reachs target
        vIndex = find(vs.Data>60,1);

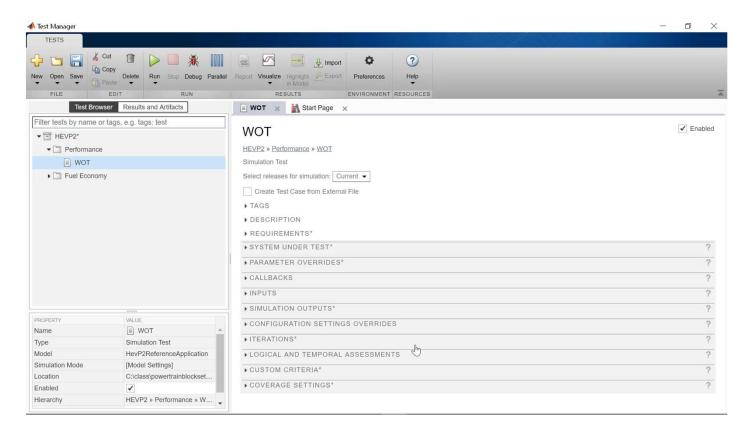
    CUSTOM CRITERIA

√ function customCriteria(test)

          ▶ Perform custom criteria analysis on test results
            wotTest.customCriteria(test);
                                                   drive cycle shall be less than 20 seconds.
                                                   NOT 0 60 MAX TIME, sprintf('0-60 test\n'));
        vIndex = find(vs.Data>40,1);
        if isempty(vIndex)
             v40Time = Inf;
        else
             v40Time = vs.Time(vIndex);
         end
        % Requirment 2
         Requirement Passing Time 60 MPH in the WOT drive cycle shall be less than 5 seconds.
        test.verifyLessThan(v60Time-v40Time, wotTest.WOT 40 60 MAX TIME, sprintf('40-60 passing test\n'));
```



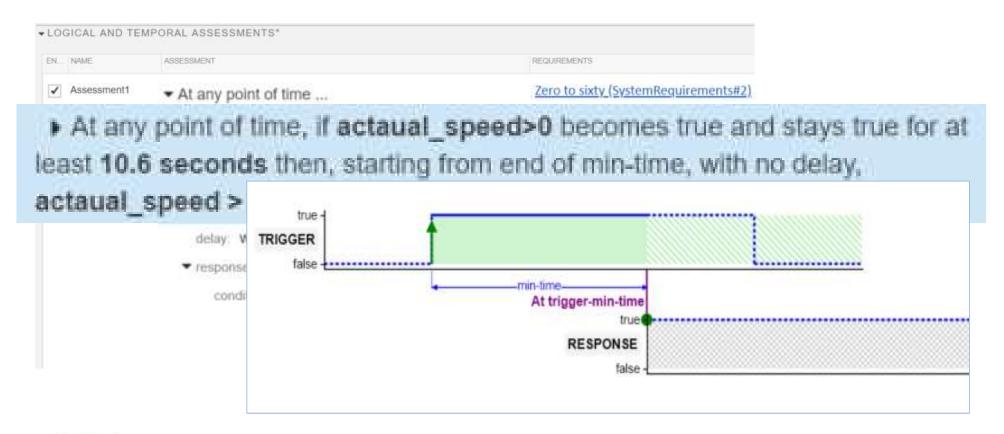
Dynamic Test for HevP2Reference Application





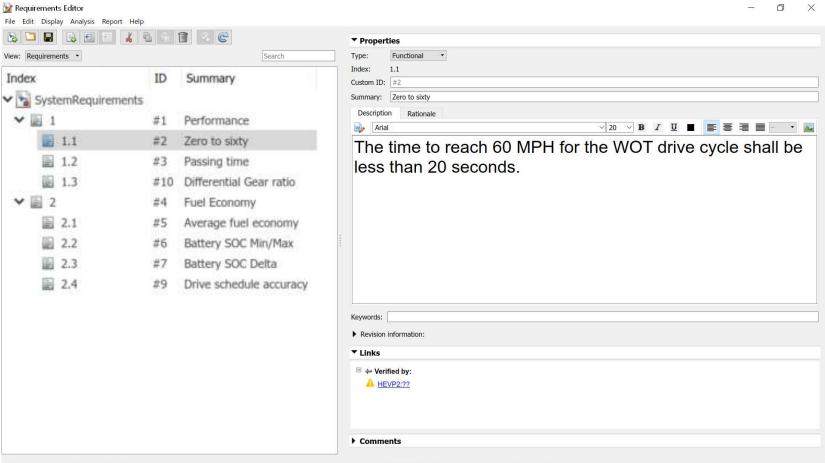
Temporal Assessment





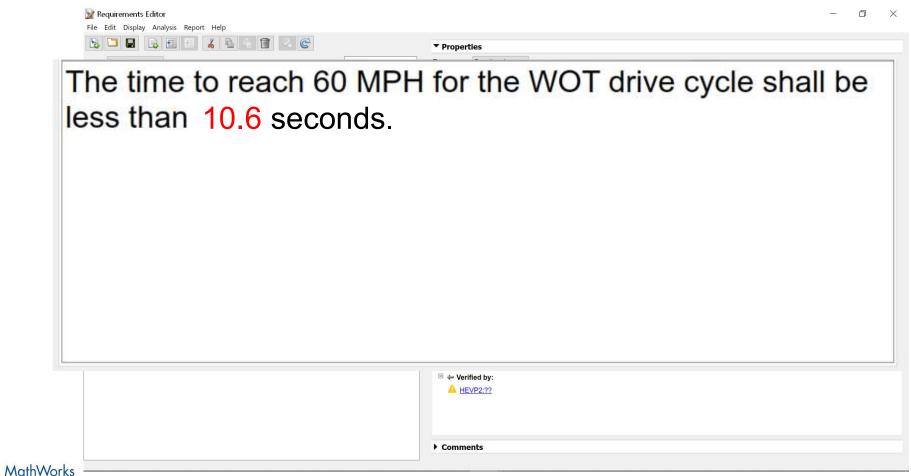


Temporal Requirement Change





Temporal Requirement Change



AUTOMOTIVE CONFERENCE 2019



Test Assessments: Formalize and execute requirements R2019a

Zero to Sixty

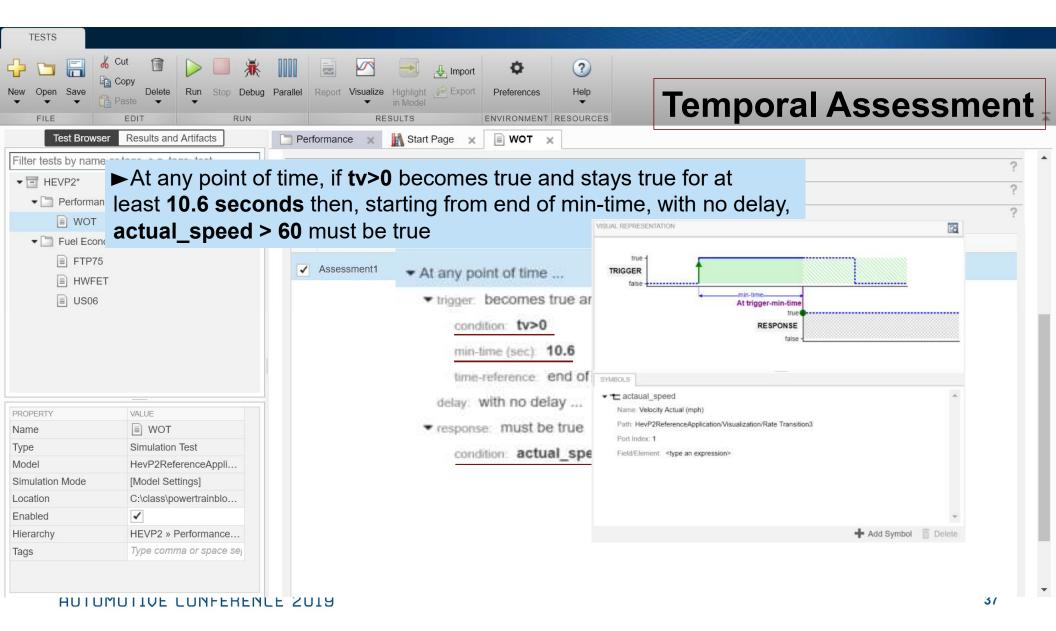
The speed shall at least reach 60MPH after 10.6 sec passes

When < condition 1> is true, Then <condition 2> must be true for some time

Simple concept

$$(|x_1 - x_2| \ge x_3)^{\frac{\varepsilon}{\leftarrow}} \land \Box_{[0,t_1)}(|x_1 - x_2| \ge x_3) \rightarrow \Box_{[0,t_2)}x_4$$
 Hard to formalize

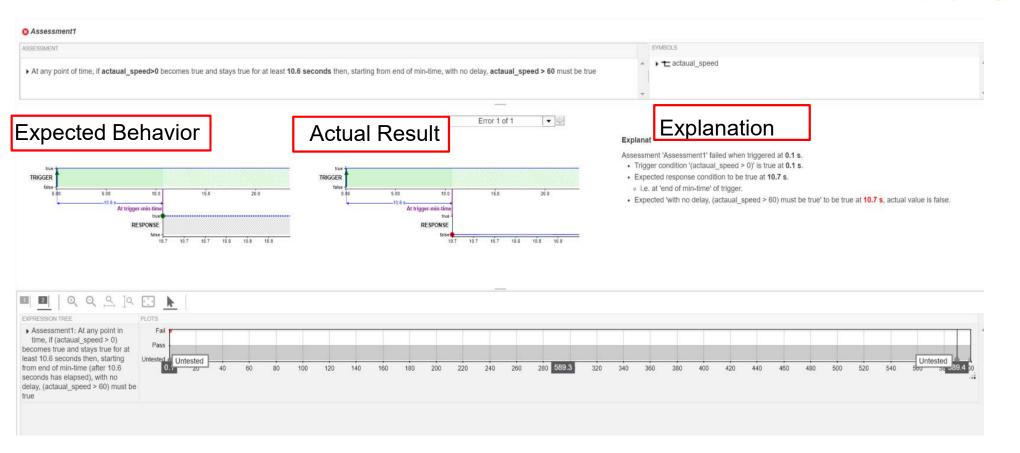
MTL logic





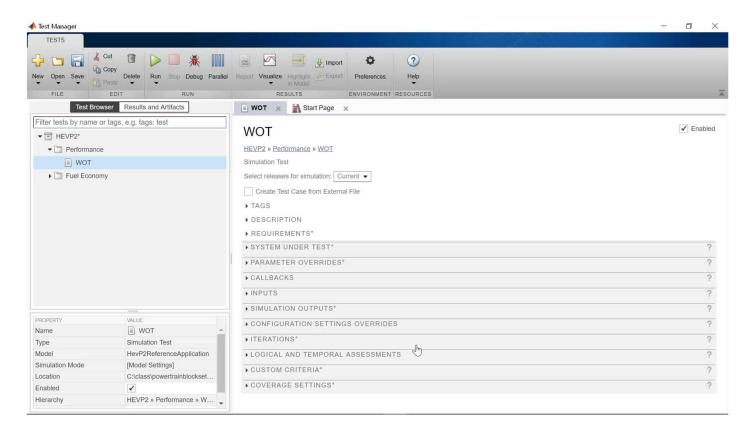
Temporal Assessment

R2019a





Dynamic Test for HevP2Reference Application





Dynamic Test 1 - Fuel Economy

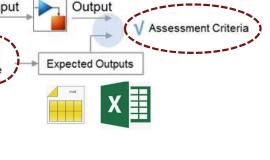
Requirement

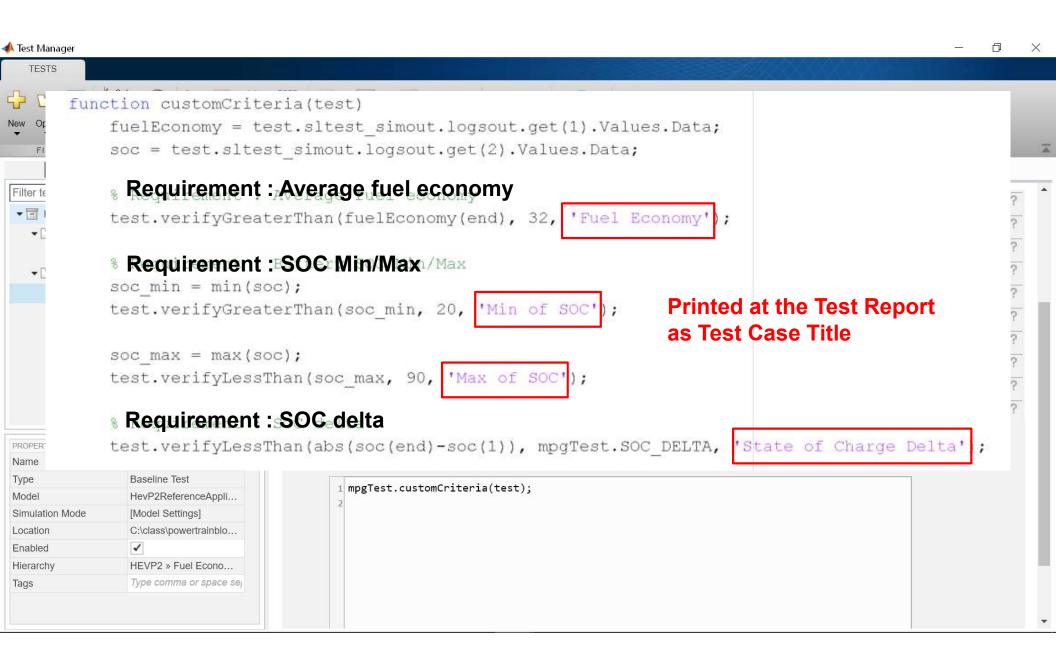
- The average fuel economy at the end of the drive profile shall be 32 MPG.
- The battery state of charge shall be greater than 20% and less than 90% for the entire drive cycle.
- The absolute value of the difference between the battery state of charge at the start of the drive profile and the end of the drive cycle shall be less than 1%.
- The actual vehicle speed shall be no more than 2 mph greater than the scheduled vehicle speed within 1 second of the given time.

mpgTest.customCriteria(test):

Configuration

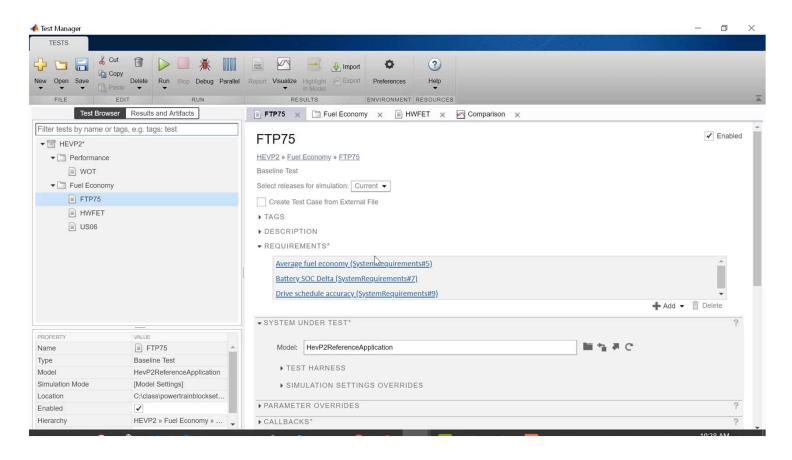
- Test Template
- Test Measureme
 - Target Speed
 - Actual Speed
 - SOC
 - MPG







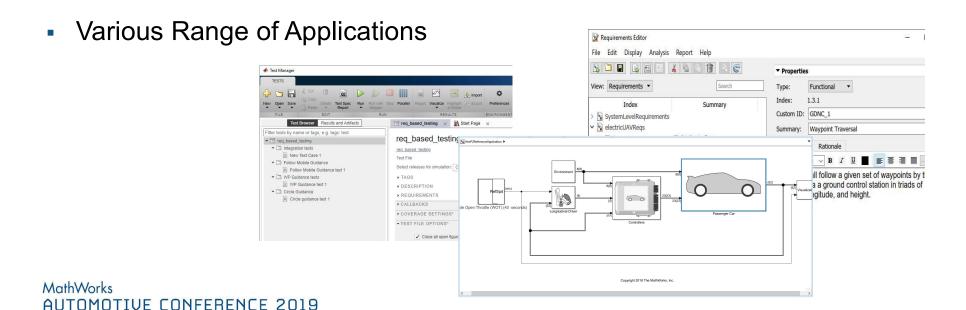
Dynamic Test for HevP2Reference Application





Key Takeaway

- Verification and Validation Process for Powertrain System
- Flexible and Automatic Verification and Validation





Thank you!